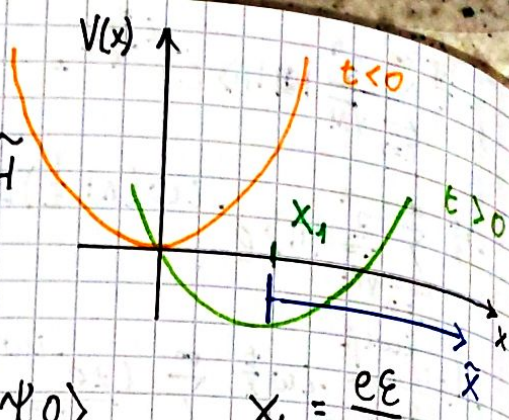


$$H(t) = \begin{cases} t < 0; & \frac{p^2}{2m} + \frac{1}{2} \mu x^2 = H \\ t > 0; & \frac{p^2}{2m} + \frac{1}{2} \mu x^2 - e \mathcal{E}_x = \tilde{H} \end{cases}$$



$$|\Psi, 0\rangle = |0\rangle \rightarrow a|\Psi, 0\rangle = 0$$

$$|\Psi, t\rangle = ? \rightarrow \tilde{a}|\Psi, 0\rangle = -\frac{x_1}{\sqrt{2}x_0} |\Psi, 0\rangle$$

$$x_1 = \frac{e\mathcal{E}}{\omega}$$

Ultravijoli svetloba je koherentnimi stanji: (ostanejo koherentna tudi skozi čas)

$$a|z\rangle = z|z\rangle$$

$$|z, t\rangle = e^{-i\frac{\omega}{2}t} |ze^{-i\omega t}\rangle$$

$$\langle x \rangle = \sqrt{2} x_0 \operatorname{Re} z$$

$$\Psi_z(x) = \frac{1}{\sqrt{\pi} x_0} e^{-\frac{(x - \sqrt{2} \mathcal{E}_0 p_{0z})^2}{2x_0}} e^{\frac{i\sqrt{2} p_{0z} z}{\hbar} x}$$

← gaussov valovni paket

Poglejmo si:

$$z(t)$$

$$z(0) = -\frac{x_1}{\sqrt{2}x_0}$$

$$z(t) = -\frac{x_1}{\sqrt{2}x_0} e^{-i\omega t}$$

$$\langle x, t \rangle = ?$$

$$\langle \tilde{x}, t \rangle = \sqrt{2} x_0 \operatorname{Re} (z(t)) =$$

$$= \sqrt{2} x_0 \operatorname{Re} \left(-\frac{x_1}{\sqrt{2}x_0} e^{-i\omega t} \right) = -x_0 \cos(\omega t)$$

Upoštevamo povezavo med x in \tilde{x} :

$$\langle x, t \rangle = -x_1 \cos(\omega t) + x_1 = x_1 (1 - \cos(\omega t))$$

To pa dobimo tudi v ulasičenem primeru

[2D Harmonijski oscilator]

$$H = \frac{p^2}{2m} + \frac{1}{2} k_x x^2 + \frac{1}{2} k_y y^2 \quad p^2 = (\vec{p})^2$$

$$\vec{p} = (p_x, p_y) = \left(-i\hbar \frac{\partial}{\partial x}, -i\hbar \frac{\partial}{\partial y}\right) = -i\hbar \nabla$$

$$p^2 = p_x^2 + p_y^2$$

Tako lahko Hamiltonian razstavimo na dva dela:

$$H = H_x + H_y$$

Separacija spremenljivk

$$\Psi(x, y) = f(x) \chi(y)$$

$$H_x f_n(x) = E_n^x f_n(x)$$

$$H_y \chi_m(y) = E_m^y \chi_m(y)$$

$$\Rightarrow H f_n(x) \chi_m(y) = (E_n^x + E_m^y) f_n(x) \chi_m(y)$$

Če poznamo obe rešitvi v 1D lahko rešimo v 2D

V Diracovem zapisu je to:

$$H |n\rangle_x |m\rangle_y = (E_n^x + E_m^y) |n\rangle_x |m\rangle_y$$

↑
prostor x

OZ.

Oznaka:

$$|n\rangle_x = |n_x\rangle$$

$$H |n m\rangle = (E_n^x + E_m^y) |n m\rangle$$

Se nanaša na x ↑ se nanaša na y

Spomnimo kako se reši LHO za 1D:

$$H_x |n_x\rangle = \hbar \omega_x \left(n_x + \frac{1}{2}\right) |n_x\rangle; \quad \omega_x = \sqrt{\frac{k_x}{m}}$$

$$H_y |n_y\rangle = \hbar \omega_y \left(n_y + \frac{1}{2}\right) |n_y\rangle; \quad \omega_y = \sqrt{\frac{k_y}{m}}$$

Tako je celotno:

$$H |n_x n_y\rangle = \hbar(\omega_x (n_x + \frac{1}{2}) + \omega_y (n_y + \frac{1}{2})) |n_x n_y\rangle$$

To vse velja $\hbar_x > 0$ in $\hbar_y > 0$

Poglejmo si primer $\hbar_x > 0$ in $\hbar_y = 0$

$$H_y = \frac{p_y^2}{2m} + 0; \text{ Konstanten potencial (rešitve so ravninski valovi)}$$

$$p_y e^{i q_y y} = \hbar q_y e^{i q_y y}$$

$$\Rightarrow H_y e^{i q_y y} = \frac{\hbar^2 q_y^2}{2m} e^{i q_y y}$$

q_y ... valovni vektor ki karakterizira ravninski val

$$H_y |q_y\rangle = \frac{\hbar^2 q_y^2}{2m} |q_y\rangle$$

Tako je 2D problem:

$$H |n_x q_y\rangle = \left[\hbar\omega_x (n_x + \frac{1}{2}) + \frac{\hbar^2 q_y^2}{2m} \right] |n_x q_y\rangle$$

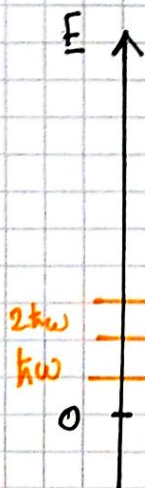
Vzimo se na splošen primer $\hbar_x > 0$ in $\hbar_y > 0$

Poglejmo si izotropni harmonski oscilator $\hbar_x = \hbar_y = \hbar$ $\omega_x = \omega_y = \omega$

$$H = \frac{p^2}{2m} + \frac{1}{2} \hbar (x^2 + y^2) = \frac{p^2}{2m} + \frac{1}{2} \hbar r^2$$

→ Odvisen je od oddaljenosti od izhodišča ampule \hbar od polarne kota

$$H |n_x n_y\rangle = \hbar\omega (n_x + n_y + 1) |n_x n_y\rangle$$



$|20\rangle, |02\rangle, |11\rangle$

$|01\rangle, |10\rangle$

$|00\rangle$

→ Degenerirano vzbujevano stanje

$$|\alpha|^2 + |\beta|^2 = 1$$

$$\alpha |10\rangle + \beta |01\rangle$$

Pokažimo, da $|01\rangle$ in $|10\rangle$ res tvorita 2D bazo prostora vseh funkcij, ki imajo energijo $2\hbar\omega$

$$H(\alpha|10\rangle + \beta|01\rangle) = \alpha H|10\rangle + \beta H|01\rangle = 2\hbar\omega(\alpha|10\rangle + \beta|01\rangle)$$

Tudi lin. komb. je lastna funkcija z isto energijo ✓

Torej: $H = \frac{p^2}{2m} + V(r)$

V smeri simetrijske osi potenciala se ohranja vrtilna količina. To se

Zapiše s komutatorjem kot:

$$[H, L_z] = 0 ; L_z = x p_y - y p_x = -i\hbar \frac{\partial}{\partial \phi}$$

Ker operatorja komutirata lahko najdemo Lastne funkcije obeh klorati.

Kateri linearne kombinacije lastnih stanj H so lastne funkcije L_z ?

Poglejmo to za 2x degenerirano 1. vzbujeno stanje.

$$L_z |\psi\rangle = \lambda |\psi\rangle$$

$$-i\hbar \frac{\partial}{\partial \phi} \psi(\phi) = \lambda \psi(\phi)$$

Resimo diferencialno enačbo

$$-i\hbar \psi'(\phi) - \lambda \psi(\phi) = 0 \Rightarrow \psi(\phi) = C e^{i \frac{\lambda}{\hbar} \phi}$$

Robni pogoj: $\psi(\phi) = \psi(\phi + 2\pi) \Rightarrow \frac{\lambda}{\hbar} = m \in \mathbb{Z}$

Tako so lastne funkcije:

$$\psi(\phi) = C e^{i m \phi}$$

iz normalizacije:

$$\int_0^{2\pi} |\psi(\phi)|^2 d\phi = 1$$

$$\psi(\phi) = \frac{1}{\sqrt{2\pi}} e^{i m \phi}$$

Pokažimo, da $|01\rangle$ in $|10\rangle$ res tvorita 2D bazo prostora vseh funkcij, ki imajo energijo $2\hbar\omega$

$$H(\alpha|10\rangle + \beta|01\rangle) = \alpha H|10\rangle + \beta H|01\rangle = 2\hbar\omega(\alpha|10\rangle + \beta|01\rangle)$$

Tudi lin. komb. je lastna funkcija, z isto energijo ✓

Torej: $H = \frac{p^2}{2m} + V(r)$

V smeri simetrijske osi potenciala se ohranja vrtilna količina. To se zapiše s komutatorjem kot:

$$[H, L_z] = 0 ; L_z = x p_y - y p_x = -i\hbar \frac{\partial}{\partial \phi}$$

Ker operatorja komutirata lahko najdemo lastne funkcije obeh klorati. Katere linearne kombinacije lastnih stanj H so lastne funkcije L_z ? Poglejmo to za 2x degenerirano 1. vzbujeno stanje.

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iz normalizacije:

$$\int_0^{2\pi} |\psi(\phi)|^2 d\phi = 1$$

$$\psi(\phi) = \frac{1}{\sqrt{2\pi}} e^{i m \phi}$$

$$\Psi_{10}(x, y) = \alpha \Psi_{10}(x, y) + \beta \Psi_{01}(x, y)$$

$$\Psi_{10}(x, y) = \Psi_1(x) \cdot \Psi_0(y)$$

$$\Psi_{01}(x, y) = \Psi_0(x) \cdot \Psi_1(y)$$

Zanima nas:

$$\Psi_0(x) = \frac{1}{\sqrt{\pi x_0^2}} e^{-\frac{x^2}{2x_0^2}}$$

$$\Psi_1(x) = ?$$

$$a^\dagger |0\rangle = |1\rangle$$

$$\Rightarrow \frac{1}{\sqrt{2}} \left(\frac{x}{x_0} - i \frac{p}{p_0} \right) \Psi_0(x) = \Psi_1(x); \quad p_x = -i\hbar \frac{d}{dx}, \quad p_0 = \frac{\hbar}{x_0}$$

Torej je:

$$\Psi_1(x) = \frac{1}{\sqrt{2}} \frac{1}{\sqrt{\pi x_0^2}} \left[\frac{x}{x_0} e^{-\frac{x^2}{2x_0^2}} - i \frac{1}{p} \left(-i\hbar \left(-\frac{2x}{2x_0^2} \right) e^{-\frac{x^2}{2x_0^2}} \right) \right] =$$

$$= \frac{1}{\sqrt{4\pi x_0^2}} e^{-\frac{x^2}{2x_0^2}} \left[\frac{x}{x_0} + \frac{x_0}{\hbar} \frac{x}{x_0^2} \right] =$$

$$x_0 = \sqrt{\frac{\hbar}{m\omega}} =: y_0$$

$$= \sqrt{2} \frac{x}{x_0} \Psi_0(x)$$

Tako lahko zapišemo Ψ_{10} in Ψ_{01} kot:

$$\Psi_{10}(x, y) = \frac{1}{\sqrt{4\pi x_0^2}} \left[\sqrt{2} \frac{x}{x_0} e^{-\frac{x^2}{2x_0^2}} \right] \frac{1}{\sqrt{\pi x_0^2}} e^{-\frac{y^2}{2x_0^2}} =$$

$$= \frac{\sqrt{2}}{\sqrt{\pi x_0^2}} \frac{x}{x_0} e^{-\frac{1}{2x_0^2} (x^2 + y^2)}$$

V polarnih koordinatah torej:

$$\Psi_{10}(r, \varphi) = \sqrt{\frac{2}{\pi x_0^2}} \frac{r \cos \varphi}{x_0} e^{-\frac{1}{2x_0^2} r^2} = \cos \varphi F(r)$$

$$\Psi_{10}(r, \varphi) = \dots = \sin \varphi F(r)$$

Rabimo dobiti
 $e^{i\varphi}$

$$|10\rangle = |01\rangle$$

$\leftarrow \rightarrow$

Poseben primer koherentnega stanja. Koherentna stanja so Gaussovski valovni paketi

$$1 \cdot \cos f + i \sin f = e^{if} \quad (m=1)$$

$$1 \cdot \cos f - i \sin f = e^{-if} \quad (m=-1)$$

$$|m=1\rangle = 1 \cdot |10\rangle + i |01\rangle$$

$$|m=-1\rangle = 1 \cdot |10\rangle - i |01\rangle$$

Te dve VF nista
Normirani

$$\left| \frac{1}{\sqrt{2}} \right|^2 + \left| \frac{i}{\sqrt{2}} \right|^2 = 1$$

Torej:

$$|m=1\rangle = \frac{1}{\sqrt{2}} (|10\rangle + i |01\rangle)$$

$$|m=-1\rangle = \frac{1}{\sqrt{2}} (|10\rangle - i |01\rangle)$$

Drug postopek za E_0 , tu je preprostejši in ni treba nič "videti"

$$|\psi\rangle = \alpha |10\rangle + \beta |01\rangle$$

$$\langle n_x n_y | n_x n_y \rangle = \delta_{n_x n_x} \delta_{n_y n_y}$$

$$L_z |\psi\rangle = \lambda |\psi\rangle$$

$$L_z (\alpha |10\rangle + \beta |01\rangle) = \lambda (\alpha |10\rangle + \beta |01\rangle)$$

• $\langle 10|$, $\langle 01|$

Projiciramo to
stanje na
 $|10\rangle$ in $|01\rangle$

$$\alpha L_z |10\rangle + \beta L_z |01\rangle = \lambda (\alpha |10\rangle + \beta |01\rangle)$$

$$a) \quad \langle 10 | \alpha L_z | 10 \rangle + \langle 10 | \beta L_z | 01 \rangle = \lambda \alpha$$

$$b) \quad \langle 01 | \alpha L_z | 10 \rangle + \langle 01 | \beta L_z | 01 \rangle = \lambda \beta$$

Sistem linearnih enačb

$$\begin{pmatrix} \langle 10 | L_z | 10 \rangle & \langle 10 | L_z | 01 \rangle \\ \langle 01 | L_z | 10 \rangle & \langle 01 | L_z | 01 \rangle \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \lambda \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$$

Problem lastnih
vrednosti in
lastnih vektorjev

↑
Matrični elementi
operatorja L_z

$$L_z = x p_y - y p_x = -i\hbar \frac{\partial}{\partial \phi}$$

Problem lahko rešimo tudi lo zapisemo z a in a^\dagger

$$H = \hbar\omega \left(a_x^\dagger a_x + \frac{1}{2} \right) + \hbar\omega \left(a_y^\dagger a_y + \frac{1}{2} \right)$$

1D HO
 $x = \frac{x_0}{\sqrt{2}} (a + a^\dagger)$ $x_0 = \sqrt{\frac{\hbar}{m\omega}}$
 $p = \frac{p_0}{\sqrt{2}i} (a - a^\dagger)$ $p_0 = \frac{\hbar}{x_0}$

Torej lahko zapisemo:

$$x = \frac{x_0}{\sqrt{2}} (a_x + a_x^\dagger) \quad y = \frac{x_0}{\sqrt{2}} (a_y + a_y^\dagger)$$

$$p_x = \frac{p_0}{\sqrt{2}i} (a_x - a_x^\dagger) \quad p_y = \frac{p_0}{\sqrt{2}i} (a_y - a_y^\dagger)$$

= in sestavimo L_z :

$$L_z = \frac{x_0}{\sqrt{2}} \frac{p_0}{\sqrt{2}i} (a_x + a_x^\dagger)(a_y - a_y^\dagger) - \frac{x_0}{\sqrt{2}} \frac{p_0}{\sqrt{2}i} (a_y + a_y^\dagger)(a_x - a_x^\dagger) =$$

$$= \frac{\hbar}{2i} \left[\underbrace{a_x a_y}_{\text{red}} - \underbrace{a_x a_y^\dagger}_{\text{blue}} + \underbrace{a_x^\dagger a_y}_{\text{green}} - \underbrace{a_x^\dagger a_y^\dagger}_{\text{orange}} - \underbrace{a_y a_x}_{\text{green}} + \underbrace{a_y a_x^\dagger}_{\text{blue}} - \underbrace{a_y^\dagger a_x}_{\text{blue}} + \underbrace{a_y^\dagger a_x^\dagger}_{\text{orange}} \right] =$$

$$= \frac{\hbar}{2i} \left[-2a_x a_y^\dagger + 2a_x^\dagger a_y \right] = \frac{\hbar}{i} (a_x^\dagger a_y - a_x a_y^\dagger)$$

$\frac{\partial^2}{\partial x \partial y} = \frac{\partial^2}{\partial y \partial x} \Rightarrow [a_x, a_y] = [a_x, a_y^\dagger] = \dots = 0$ Komutirajo

Sedaj lahko izračunamo matrične elemente:

$$\langle 10 | L_z | 10 \rangle = \langle 10 | \frac{\hbar}{i} (a_x^\dagger a_y - a_x a_y^\dagger) | 10 \rangle =$$

Deluje na

$$= \frac{\hbar}{i} \left(\langle 10 | a_x^\dagger a_y | 10 \rangle - \langle 10 | a_x a_y^\dagger | 10 \rangle \right) =$$

$$a_x^\dagger a_y | 10 \rangle = a_x^\dagger a_y | 1 \rangle_x | 0 \rangle_y =$$

$$= (a_x^\dagger | 1 \rangle_x) (a_y | 0 \rangle_y) = \sqrt{2} | 2 \rangle_x \cdot 0 = 0$$

Zaradi ort.

$$= \frac{\hbar}{i} \langle 10 | (0 - | 01 \rangle) = -\frac{i}{\hbar} \langle 10 | 01 \rangle = 0$$

$$\langle 10 | 01 \rangle = \langle 1 | 0 \rangle_x \langle 0 | 1 \rangle_y = 0 \cdot 0 = 0$$

Poglejmo si še:

$$L_z |10\rangle = \frac{\hbar}{i} (-101)$$

$$\Rightarrow \langle 01 | L_z | 10 \rangle = -\frac{\hbar}{i} \langle 01 | 01 \rangle = i\hbar$$

$$L_z |01\rangle = \frac{\hbar}{i} (a_x^\dagger a_y - a_x a_y^\dagger) |01\rangle = \frac{\hbar}{i} (|110\rangle - 0) = \frac{\hbar}{i} |110\rangle$$

Še zadnja dva elementa data torej:

$$\langle 10 | L_z | 01 \rangle = \frac{\hbar}{i} \langle 10 | 10 \rangle = -i\hbar$$

$$\langle 01 | L_z | 01 \rangle = \frac{\hbar}{i} \langle 01 | 10 \rangle = 0$$

Torej imamo problem diagonalizacije matrice:

$$\begin{bmatrix} 0 & -i\hbar \\ i\hbar & 0 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \lambda \begin{bmatrix} \alpha \\ \beta \end{bmatrix}$$

Diagonalizirajmo to matriko

$$\det \begin{bmatrix} 0-\lambda & -i\hbar \\ i\hbar & 0-\lambda \end{bmatrix} = 0 = \lambda^2 + (-i\hbar)^2 = \lambda^2 - \hbar^2 \Rightarrow \lambda_{1,2} = \pm \hbar$$

Poiščimo še lastne vektorje

$$\begin{bmatrix} -\hbar & -i\hbar \\ i\hbar & -\hbar \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = 0$$

$$\begin{aligned} -\alpha - i\beta &= 0 & \Rightarrow & \alpha = -i\beta \\ i\alpha - \beta &= 0 & \Rightarrow & \beta = i\alpha \end{aligned} \Rightarrow \begin{aligned} |\alpha|^2 + |\beta|^2 &= 0 \\ |-i\beta|^2 + |\beta|^2 &= 1 \\ 2|\beta|^2 &= 1 \\ \beta &= \pm \frac{1}{\sqrt{2}} \end{aligned}$$

Da dobimo enolično rešitev
Uporabimo še normalizacijo
 $|\alpha|^2 + |\beta|^2 = 1$

$$\text{Torej je } N_1 = \begin{bmatrix} -i\beta \\ \beta \end{bmatrix} = \begin{bmatrix} -\frac{i}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

Ponovimo še za λ_2 :

$$\begin{bmatrix} \hbar & -i\hbar \\ i\hbar & \hbar \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = 0 \rightarrow \alpha = -i\beta \xrightarrow{\text{Norm.}} \begin{bmatrix} i\beta \\ \beta \end{bmatrix}$$

$$V_2 = \begin{bmatrix} \frac{i}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

Za L_z vemo: $L_z |m\rangle = \hbar m |m\rangle$

Lastne vrednosti
operatorja VK

$$|1\rangle = \frac{1}{\sqrt{2}} (-i|10\rangle + |01\rangle)$$

$$\therefore |-1\rangle = \frac{1}{\sqrt{2}} (i|10\rangle + |01\rangle)$$

To je od zadnjic zamaljen rezultat za fazo $(-i)$. To je matematično drugačen rezultat, ampak je fizično čisto enako.

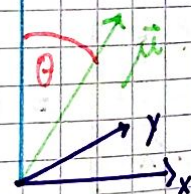
[Kvanten ekvivalent precesije magnetnega momenta doli mag. polja] $\vec{z} \uparrow \vec{B}$

~~Hamiltonian~~

$$H = -\vec{\mu} \cdot \vec{B}; \quad \vec{\mu} = -\mu_B \frac{\vec{L}}{\hbar}$$

\Downarrow

$$H = \lambda \vec{L} \cdot \vec{B}$$



Za $l=1$ ustreza 3D Hilbertov prostor:

Baza:

$$L^2 |lm\rangle = \hbar^2 l(l+1) |lm\rangle$$

$$|11\rangle$$

$$L_z |lm\rangle = \hbar m |lm\rangle$$

$$|10\rangle$$

$$|1-1\rangle$$

$m=1$ $L_z |11\rangle = \hbar |11\rangle$ "kaže v smeri z"

$$\vec{L} \hat{e}_z |11\rangle = \hbar |11\rangle \quad \vec{L} = (L_x, L_y, L_z)$$

Torej

Začetni pogoj

$$\vec{L} \cdot \hat{n} |\Psi, 0\rangle = \hbar |\Psi, 0\rangle$$

$$|\Psi, t\rangle = ?$$

$$|N, 0\rangle = \alpha|11\rangle + \beta|10\rangle + \gamma|1-1\rangle$$

Na začetu lahko zapišemo normalo ($\varphi = 0^\circ$)

$$\hat{n} = \begin{bmatrix} \sin\theta \cos\varphi \\ \sin\theta \sin\varphi \\ \cos\theta \end{bmatrix} = \begin{bmatrix} \sin\theta \\ 0 \\ \cos\theta \end{bmatrix}$$

Izračunamo:

$$\vec{L} \cdot \hat{n} = L_x \sin\theta + L_z \cos\theta$$

Torej:

$$(L_x \sin\theta + L_z \cos\theta)(\alpha|11\rangle + \beta|10\rangle + \gamma|1-1\rangle) = \hbar(\alpha|11\rangle + \beta|10\rangle + \gamma|1-1\rangle)$$

To je spet problem lastnih vrednosti ker je lastna vrednost (cm) določena z začetnim pogojem.

Vpeljamo (s podobno vlogo kot a in a^\dagger pri LHO):

$$L_{\pm} = L_x \pm iL_y$$

$$L_x = \frac{L_+ + L_-}{2}$$

$$L_y = \frac{L_+ - L_-}{2i}$$

$$L_{\pm} |l, m\rangle = \hbar \sqrt{l(l+1) - m(m \pm 1)} |l, m \pm 1\rangle$$

To stanje ne obstaja

$$l; m = -l, \dots, l$$

$$L_x |11\rangle = \frac{L_+ + L_-}{2} |11\rangle = \frac{1}{2} \hbar (\sqrt{2-2} |12\rangle + \sqrt{2-0} |10\rangle)$$

$$L_x |10\rangle = \frac{\hbar}{2} (\sqrt{2} |11\rangle + \sqrt{2} |1-1\rangle) = \frac{\sqrt{2}}{2} \hbar (|11\rangle + |1-1\rangle)$$

$$L_x |1-1\rangle = \frac{\hbar}{2} (\sqrt{2} |10\rangle) = \frac{\sqrt{2}}{2} \hbar |10\rangle$$

$$L_z |11\rangle = \hbar |11\rangle$$

$$L_z |10\rangle = 0$$

$$L_z |1-1\rangle = -\hbar |1-1\rangle$$

To je sedaj konec stranskega ravnine, vrnemo se nazaj

$$\sin\theta \frac{\sqrt{2}}{2} \hbar (\alpha |10\rangle + \beta |11\rangle + \beta |1-1\rangle + \gamma |10\rangle) +$$

$$+ \cos\theta \hbar (\alpha |11\rangle + \gamma |1-1\rangle) = \hbar (\alpha |11\rangle + \beta |10\rangle + \gamma |1-1\rangle)$$

Iz tega lahko dobimo ven 3 enačbe (zaradi ortogonalnosti)

$$|10\rangle: \sin\theta \frac{\sqrt{2}}{2} \hbar (\alpha + \gamma) = \hbar \beta$$

$$|11\rangle: \sin\theta \frac{\sqrt{2}}{2} \hbar \beta + \cos\theta \hbar \alpha = \hbar \alpha$$

$$|1-1\rangle: \sin\theta \frac{\sqrt{2}}{2} \hbar \beta - \gamma \cos\theta \hbar = -\hbar \gamma$$

To so že enačbe za
določitev lastnega
vektora.

$$\beta = \sin\theta \frac{\sqrt{2}}{2} (\alpha + \gamma)$$

$$\sin\theta = 2 \sin\frac{\theta}{2} \cos\frac{\theta}{2}$$

$$\alpha = \frac{-\sin\theta \frac{\sqrt{2}}{2}}{\cos\theta - 1} \beta = \beta \frac{\sqrt{2} \sin\frac{\theta}{2} \cos\frac{\theta}{2}}{2 \sin^2\frac{\theta}{2}}$$

$$1 + \cos\theta = 2 \cos^2\frac{\theta}{2}$$

$$1 - \cos\theta = 2 \sin^2\frac{\theta}{2}$$

$$\gamma = \frac{\sin\theta \frac{\sqrt{2}}{2}}{\cos\theta + 1} \beta =$$

$$\left. \begin{aligned} &= \frac{\sqrt{2}}{2} \operatorname{ctg}\frac{\theta}{2} \beta \end{aligned} \right\}$$

$$= \frac{\sqrt{2} \sin\frac{\theta}{2} \cos\frac{\theta}{2}}{2 \cos^2\frac{\theta}{2}} = \frac{\sqrt{2}}{2} \operatorname{tg}\frac{\theta}{2} \beta$$

Torej vmesno:

$$|4,0\rangle = \frac{\sqrt{2}}{2} \operatorname{ctg}\frac{\theta}{2} \beta |11\rangle + \beta |10\rangle + \frac{\sqrt{2}}{2} \operatorname{tg}\frac{\theta}{2} \beta |1-1\rangle$$

β pa dobimo iz normalizacije:

$$\left(\frac{1}{2} \operatorname{ctg}^2\frac{\theta}{2} + 1 + \frac{1}{2} \operatorname{tg}^2\frac{\theta}{2} \right) |\beta|^2 = 1$$

Torej:

$$\frac{\cos^4 \frac{\theta}{2} + 2 \sin^2 \frac{\theta}{2} \cos^2 \frac{\theta}{2} + \sin^4 \frac{\theta}{2}}{2 \sin^2 \frac{\theta}{2} \cos^2 \frac{\theta}{2}} = \frac{(\cos^2 \frac{\theta}{2} + \sin^2 \frac{\theta}{2})^2}{2 \sin^2 \frac{\theta}{2} \cos^2 \frac{\theta}{2}} = \frac{1}{2 \sin^2 \frac{\theta}{2} \cos^2 \frac{\theta}{2}}$$

$$\Rightarrow \beta = \sqrt{2} \sin \frac{\theta}{2} \cos \frac{\theta}{2}$$

Torej imamo na začetku:

$$|\Psi, 0\rangle = \cos^2 \frac{\theta}{2} |1, 1\rangle + \sqrt{2} \sin \frac{\theta}{2} \cos \frac{\theta}{2} |1, 0\rangle + \sin^2 \frac{\theta}{2} |1, -1\rangle$$

Rabimo časovni razvoj. Najlažje ga dobimo kot razvoj po lastnih stanjih Hamiltoniana

Torej so l. stanja L_z tudi l. stanja H

$$H = \lambda \vec{L} \cdot \vec{B} = \lambda B L_z$$

$\uparrow \vec{B} = (0, 0, B)$

$$L_z |l, m\rangle = \hbar m |l, m\rangle$$

$$H |1, 1\rangle = \lambda B \hbar |1, 1\rangle \quad H |1, 0\rangle = 0 |1, 0\rangle \quad H |1, -1\rangle = -\lambda B \hbar |1, -1\rangle$$

Tako brez težav zapisemo časovni razvoj:

$$|\Psi, t\rangle = \cos^2 \frac{\theta}{2} e^{-i\lambda B t} |1, 1\rangle + \sqrt{2} \sin \frac{\theta}{2} \cos \frac{\theta}{2} |1, 0\rangle + \sin^2 \frac{\theta}{2} e^{i\lambda B t} |1, -1\rangle$$

Poskusimo izračunati, kaj pomeni ta valovna funkcija.

$$L_z |l, m\rangle = \hbar m |l, m\rangle$$

$$\langle \vec{L}, t \rangle = ?$$

$$\langle L_z, t \rangle = \langle \Psi, t | L_z | \Psi, t \rangle =$$

$$L_z |\Psi, t\rangle = \cos^2 \frac{\theta}{2} e^{-i\lambda B t} \hbar |1, 1\rangle + 0 - \hbar \sin^2 \frac{\theta}{2} e^{i\lambda B t} |1, -1\rangle$$

$$\langle L_z, t \rangle = \hbar \left(\cos^4 \frac{\theta}{2} - \sin^4 \frac{\theta}{2} \right) = \hbar \left(\cos^2 \frac{\theta}{2} - \sin^2 \frac{\theta}{2} \right) \left(\cos^2 \frac{\theta}{2} + \sin^2 \frac{\theta}{2} \right) =$$

$$= \hbar \cos \theta$$

$$\langle L_x, t \rangle = \left\langle \frac{L_+ + L_-}{2}, t \right\rangle = \frac{1}{2} \langle L_+, t \rangle + \frac{1}{2} \langle L_-, t \rangle =$$

$$= \text{Re}(\langle L_+, t \rangle)$$

← com. conj tega

$$\langle L_-, t \rangle = \langle L_+, t \rangle^*$$

$$\langle L_y, t \rangle = \left\langle \frac{L_+ - L_-}{2i}, t \right\rangle = \frac{1}{2i} [\langle L_+, t \rangle - \langle L_-, t \rangle] =$$

$$= \text{Im}(\langle L_+, t \rangle)$$

$$\langle L_+, t \rangle = \langle \Psi, t | L_+ | \Psi, t \rangle$$

$$L_{\pm} |l, m\rangle = \hbar \sqrt{l(l+1) - m(m \pm 1)} |l, m \pm 1\rangle$$

$$L_+ | \Psi, t \rangle = 0 + 2 \sin \frac{\theta}{2} \cos \frac{\theta}{2} \hbar |1, 1\rangle + \hbar \sqrt{2} \sin \frac{2\theta}{2} e^{i\lambda B t} |1, 0\rangle$$

$$L_+ |1, -1\rangle = \hbar \sqrt{2} |1, 0\rangle$$

$$L_+ |1, 0\rangle = \sqrt{2} \hbar |1, 1\rangle$$

$$L_+ |1, 1\rangle = 0$$

$$\Rightarrow \langle L_+, t \rangle = 2 \cos^3 \frac{\theta}{2} \sin \frac{\theta}{2} e^{i\lambda B t} \hbar + 2 \hbar \sin \frac{3\theta}{2} \cos \frac{\theta}{2} e^{i\lambda B t} =$$

$$= 2 \hbar e^{i\lambda B t} \cos \frac{\theta}{2} \sin \frac{\theta}{2} (\cos^2 \frac{\theta}{2} + \sin^2 \frac{\theta}{2}) =$$

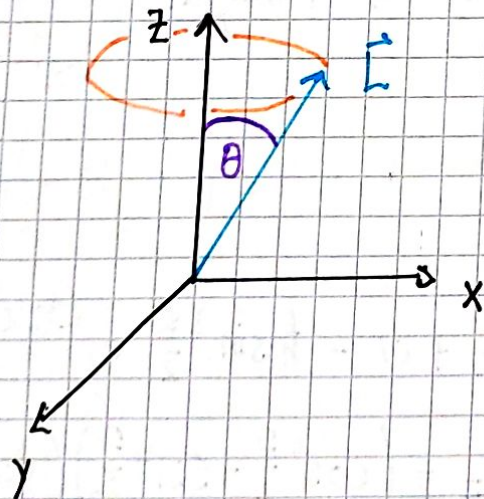
$$= 2 \hbar \sin \theta e^{i\lambda B t}$$

Tako lahko dobimo L_x in L_y

$$\langle L_x, t \rangle = \text{Re} \langle L_+, t \rangle = \hbar \cos(\lambda B t) \sin \theta$$

$$\langle L_y, t \rangle = \text{Im} \langle L_+, t \rangle = \hbar \sin(\lambda B t) \sin \theta$$

Vektorji tvorj precesira po stožcu:



To je kot klasično za vrtilno količino. Temu se v kvantni reše Larmorjeva precesija. Vrtilna količina precesira z Larmorjevo frekvenco

$$\omega_L = \lambda B$$

Kaj pa bi nam dala meritev L_z ?

Razvijemo VF po lastnih stanjih ~~meritve~~ operatorja, kar že imamo.
Možne vrednosti so lastne vrednosti operatorja. Verjetnost pa iz koeficientov pred.

L_z	$ C_m ^2$	N ob $t=0$
\hbar	$\cos^4 \frac{\theta}{2}$	$ 11\rangle$
0	$2 \cos^2 \frac{\theta}{2} \sin^2 \frac{\theta}{2}$	$ 10\rangle$
$-\hbar$	$\sin^4 \frac{\theta}{2}$	$ 1-1\rangle$

Kaj se zgodi z delcem takoj po meritvi?

Meritev kolapsira VF torej je valovna funkcija le tisto stanje, ki ustreza lastni vrednosti, ki smo jo izmerili.

Če želimo izmeriti pričakovano vrednost to ne moremo ~~na~~ narediti več meritev. Če naredimo več zaporednih meritev na enem delcu dobimo vedno tisto kar smo prvo izmerili zaradi kolapsa valovne funkcije.
Zato moramo vsakič začeti ob $t=0$ z novo generiranim začetnim stanjem.

$$\bar{L}_z = \hbar \cos^4 \frac{\theta}{2} + 0 - \hbar \sin^4 \frac{\theta}{2} = \dots = \hbar \cos \theta$$

Torej je pričakovana vrednost $\langle L_z, t \rangle$ povprečje neodvisnih meritev.

Spin

$$H = \frac{\vec{p}^2}{2m} + \lambda(p_x S_y - p_y S_x); \quad S = \frac{1}{2}$$

$$\vec{p} = (p_x, p_y) \text{ 2D}$$

Roshova ~~komutator~~
Suboperator

Rešujemo

$$H|\Psi\rangle = E|\Psi\rangle$$

$$[H, \vec{p}] = ?$$

$$[H, p_x] = \left[\frac{p_x^2}{2m} + \frac{p_y^2}{2m} + \lambda(p_x S_y - p_y S_x), p_x \right] = 0$$

v drugem podprostoru
torej redko komutira

Potem lahko iščemo ~~na~~ stanje z lastnim stanji \vec{p} :

$$\vec{p}|\vec{u}\rangle = \hbar\vec{u}|\vec{u}\rangle$$

$$\psi_{\vec{u}}(\vec{r}) = e^{i\vec{u}\cdot\vec{r}}$$

$$\vec{p} = -i\hbar\nabla$$

Torej zaradi komutiranja H in \vec{p} lahko iščemo rešitve z produktno nastavitvijo:

$$|\Psi\rangle = |\vec{u}\rangle |\chi\rangle$$

krajšava del

Spinski del

$$\left[\frac{p^2}{2m} + \lambda(p_x S_y - p_y S_x) \right] |\vec{u}\rangle |\chi\rangle = E |\vec{u}\rangle |\chi\rangle =$$

$$\left(\frac{p^2}{2m} |\vec{u}\rangle \right) |\chi\rangle + \lambda(p_x |\vec{u}\rangle)(S_y |\chi\rangle) - \lambda(p_y |\vec{u}\rangle)(S_x |\chi\rangle) = \dots$$

$$\frac{\hbar^2 u^2}{2m} |\vec{u}\rangle |\chi\rangle + \lambda(\hbar u_x |\vec{u}\rangle S_y |\chi\rangle) - \lambda(\hbar u_y |\vec{u}\rangle S_x |\chi\rangle) = E |\vec{u}\rangle |\chi\rangle$$

Dobimo:

$$\frac{\hbar^2 \omega^2}{2m} |\chi\rangle + \lambda \hbar (\omega_x S_y |\chi\rangle - \omega_y S_x |\chi\rangle) = E |\chi\rangle$$

Torej zaradi $[H, \hat{p}] = 0$ smo problem iz ∞ dim na 2D problem v spinskem prostoru.

$$S = \frac{1}{2}$$

$$|\frac{1}{2}, \frac{1}{2}\rangle = |\uparrow\rangle$$

$$|\frac{1}{2}, -\frac{1}{2}\rangle = |\downarrow\rangle$$

$$S_x = \frac{S_+ + S_-}{2}$$

$$S_y = \frac{S_+ - S_-}{2i}$$

Torej je nastavek za $|\chi\rangle$ lin komb.:

$$|\chi\rangle = \alpha |\uparrow\rangle + \beta |\downarrow\rangle$$

$$S_+ |\uparrow\rangle = 0$$

$$S_+ |\downarrow\rangle = \hbar \sqrt{\frac{1}{2} \cdot \frac{3}{2} + \frac{1}{2} \cdot \frac{1}{2}} |\uparrow\rangle = \hbar |\uparrow\rangle$$

$$S_- |\uparrow\rangle = \hbar |\downarrow\rangle$$

$$S_- |\downarrow\rangle = 0$$

Tako:

$$S_x |\uparrow\rangle = \frac{\hbar}{2} |\downarrow\rangle$$

$$S_x |\downarrow\rangle = \frac{\hbar}{2} |\uparrow\rangle$$

$$S_y |\uparrow\rangle = \frac{\hbar}{2i} |\downarrow\rangle$$

$$S_y |\downarrow\rangle = \frac{\hbar}{2i} |\uparrow\rangle$$

$$\Rightarrow \frac{\hbar^2 \omega^2}{2m} (\alpha |\uparrow\rangle + \beta |\downarrow\rangle) + \lambda \hbar \left(\omega_x \frac{\hbar}{2i} (-\alpha |\downarrow\rangle + \beta |\uparrow\rangle) - \omega_y \frac{\hbar}{2} (\alpha |\downarrow\rangle + \beta |\uparrow\rangle) \right) = E (\alpha |\uparrow\rangle + \beta |\downarrow\rangle)$$

Iz ujemajučih koeficientov dobimo dve linearni enačbi:

$$\frac{\hbar^2 \omega^2}{2m} \alpha + \lambda \hbar \beta \left(\omega_x \frac{\hbar}{2i} - \omega_y \frac{\hbar}{2} \right) = E \alpha$$

$$\frac{\hbar^2 \omega^2}{2m} \beta + \lambda \hbar \alpha \left(-\omega_x \frac{\hbar}{2i} - \omega_y \frac{\hbar}{2} \right) = E \beta$$

To je problem lastnih vrednosti:

$$\begin{pmatrix} \frac{\hbar^2 \omega^2}{2m} - E & \frac{\lambda \hbar^2}{2} \left(\frac{\omega_x}{i} - \omega_y \right) \\ -\frac{\lambda \hbar^2}{2} \left(\frac{\omega_x}{i} + \omega_y \right) & \frac{\hbar^2 \omega^2}{2m} - E \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = E \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$$

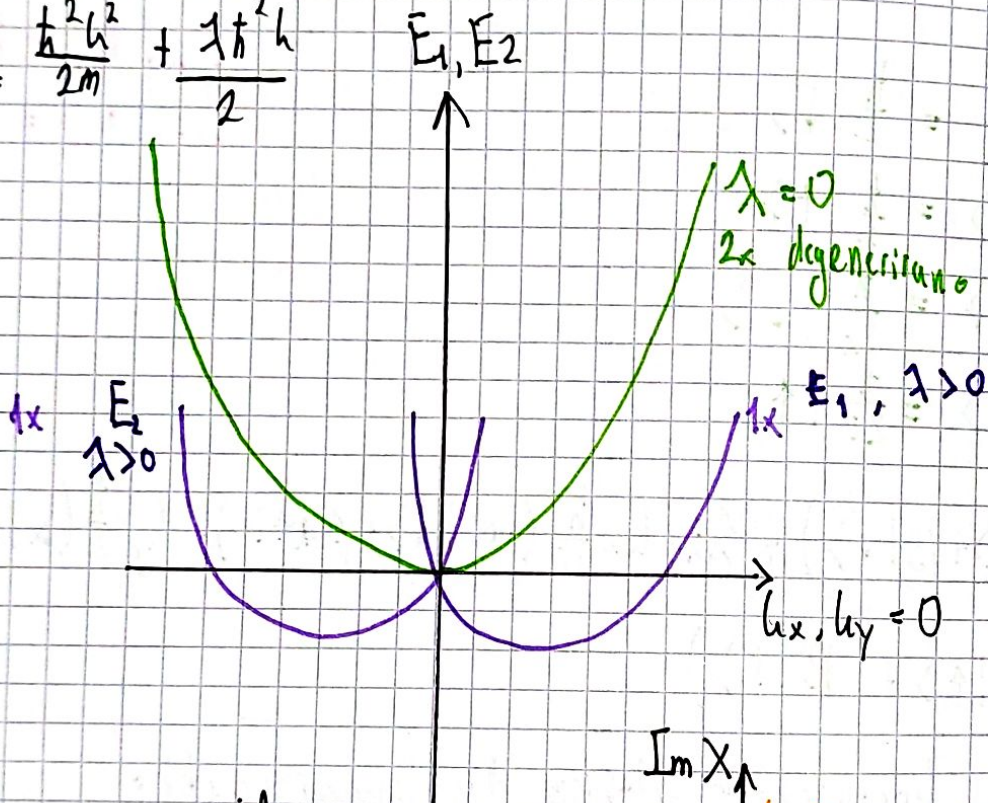
$$\begin{vmatrix} \frac{\hbar^2 k^2}{2m} - E & \frac{\lambda \hbar^2}{2} \left(\frac{k_x}{i} - k_y \right) \\ \frac{\lambda \hbar^2}{2} \left(-\frac{k_x}{i} - k_y \right) & \frac{\hbar^2 k^2}{2m} - E \end{vmatrix} = 0$$

$$\left(\frac{\hbar^2 k^2}{2m} - E \right)^2 + \frac{\lambda^2 \hbar^4}{4} \underbrace{\left(\frac{k_x}{i} - k_y \right) \left(\frac{k_x}{i} + k_y \right)}_{-k_x^2 - k_y^2 = -k^2} =$$

$$= \left(\frac{\hbar^2 k^2}{2m} - E - \frac{\lambda \hbar^2 k}{2} \right) \left(\frac{\hbar^2 k^2}{2m} - E + \frac{\lambda \hbar^2 k}{2} \right)$$

$$\Rightarrow E_1 = \frac{\hbar^2 k^2}{2m} - \frac{\lambda \hbar^2 k}{2}$$

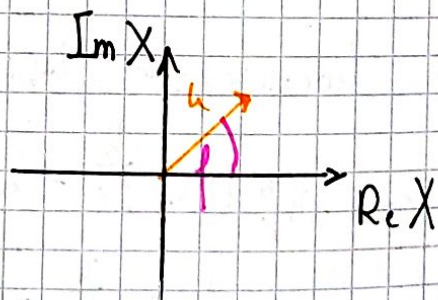
$$E_2 = \frac{\hbar^2 k^2}{2m} + \frac{\lambda \hbar^2 k}{2}$$



$$k_x + i k_y = X = k e^{i\phi}$$

$$\frac{k_x}{i} - k_y = \frac{1}{i} (k_x - i k_y) = k e^{-i\phi} \cdot \frac{1}{i}$$

$$-\frac{k_x}{i} - k_y = -\frac{1}{i} e^{i\phi} k$$



Tony za E_1

$$\begin{pmatrix} \frac{\lambda \hbar^2 \hbar}{2} & \frac{\lambda \hbar^2}{2} \frac{1}{i} \hbar e^{-i\phi} \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = 0$$

$$\lambda \hbar^2 \left(\frac{\hbar}{2} \alpha + \frac{\hbar}{2i} e^{-i\phi} \beta \right) = 0 \Rightarrow \beta = -i \alpha e^{i\phi}$$

in

$$|\alpha|^2 + |\beta|^2 = 1$$

$$\Rightarrow E_1 \Rightarrow \frac{|\uparrow\rangle - ie^{i\phi} |\downarrow\rangle}{\sqrt{2}}$$

za E_2 pa na hitro

$$E_2 \Rightarrow \frac{|\uparrow\rangle + ie^{i\phi} |\downarrow\rangle}{\sqrt{2}}$$

$$\alpha |\uparrow\rangle + \beta |\downarrow\rangle = \cos \frac{\theta}{2} |\uparrow\rangle + \sin \frac{\theta}{2} e^{i\phi} |\downarrow\rangle$$

Blochova sfera

$$|\alpha|^2 + |\beta|^2 = 1$$

$$\alpha \in \mathbb{R} \text{ in } \alpha \geq 0$$

(*) Razberimo α, β za naš primer

$$\cos \frac{\theta}{2} = \frac{1}{\sqrt{2}} \Rightarrow \theta = \frac{\pi}{2}$$

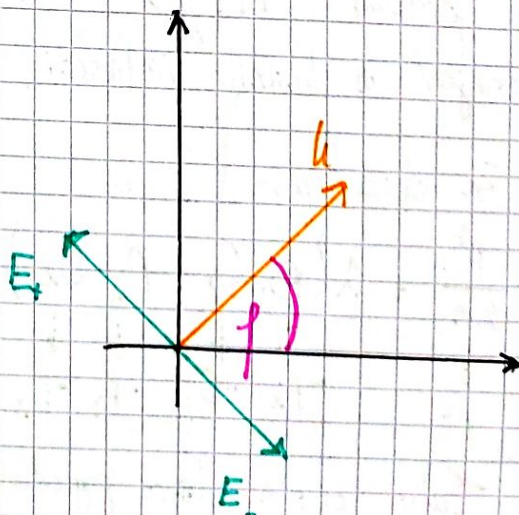
$$\frac{ie^{i\phi}}{\sqrt{2}} = \sin \frac{\theta}{2} e^{i\phi}$$

$$ie^{i\phi} = e^{i\phi} \Rightarrow \phi = \frac{\pi}{2}$$

za drugo stanje pa podobno:

$$\theta = \frac{\pi}{2}$$

$$\phi = \frac{\pi}{2}$$



[Rešimo isto nalogo z Paulijevimi matrikami]

Delo samo za spin 1/2
prejšnji postopek pa za
splošen spin

$$\alpha|\uparrow\rangle + \beta|\downarrow\rangle \rightarrow \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$$

Dirac Spinor

$$\vec{S} = (S_x, S_y, S_z) = \frac{\hbar}{2} (\sigma_x, \sigma_y, \sigma_z)$$

$$\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Prepišimo Hamiltonian z Paulijevimi matrikami:

$$H = \frac{p^2}{2m} \mathbb{I}_2 + \frac{\lambda \hbar}{2} (p_x \sigma_y - p_y \sigma_x)$$

2x2 identiteta ker p
ne deluje na spine

Kot zadnji uporabimo nastavek $|\Psi\rangle = |\vec{h}\rangle |\chi\rangle$

$$\Rightarrow H = \frac{\hbar^2 k^2}{2m} + \frac{\lambda \hbar}{2} (\hbar k_x \sigma_y - \hbar k_y \sigma_x) =$$

$$= \begin{pmatrix} \frac{\hbar^2 k^2}{2m} & \frac{\lambda \hbar^2}{2} (-i k_x - k_y) \\ \frac{\lambda \hbar^2}{2} (i k_x - k_y) & \frac{\hbar^2 k^2}{2m} \end{pmatrix}$$

Reševali bi problem $H|\Psi\rangle = E|\Psi\rangle$ in dobimo spet problem lastnih vektorjev in lastnih vrednosti, ki smo ga tudi zadnjič dobili.

[Poglejmo še obrat časa]

$$H = \frac{p^2}{2m} + \lambda (p_x S_y - p_y S_x)$$

Obrat:

$$\begin{matrix} \downarrow & \downarrow & \downarrow & \downarrow & \downarrow \\ p^2 & -p_x & -S_y & -p_y & -S_x \end{matrix}$$

Tako smo na hitro pogledali invarianco

Pogledamo si to invarianco še formalno:

$$H = \frac{p^2}{2m} + \frac{\hbar}{2} (p_x \partial_y - p_y \partial_x)$$

$$T = i \partial_y K$$

Operator obrata časa

T je antiunitaren

Operator kompleksne konjugacije

$$\langle T\phi | T\psi \rangle = \langle \phi | \psi \rangle^*$$

$$K | \vec{u} \rangle = | -\vec{u} \rangle$$

$$K e^{i\vec{u} \cdot \vec{r}} = e^{-i\vec{u} \cdot \vec{r}}$$

$$K \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} \alpha^* \\ \beta^* \end{pmatrix}$$

Da je H formalno invarianten na obrat časa mora veljati:

$$[H, T] = 0 \Rightarrow HT = TH$$

$$i \partial_y K \left(\frac{p^2}{2m} + \frac{\hbar}{2} (p_x \partial_y - p_y \partial_x) \right) = i \partial_y \left(\frac{p^2}{2m} + \frac{\hbar}{2} (-p_x \partial_y) K - (-p_y) (\partial_x) K \right)$$

$p^2 = -\frac{\hbar^2}{2m} \nabla^2 \in \mathbb{R}$
 $\begin{matrix} \rightarrow p_x = -i\hbar \frac{\partial}{\partial x} \\ \rightarrow p_y = -i\hbar \frac{\partial}{\partial y} \end{matrix}$
 $\begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$

$$= i \partial_y \left(\frac{p^2}{2m} + \frac{\hbar}{2} (-p_x (-\partial_y) - (-p_y) (\partial_x)) \right) K = (*)$$

Velja:

$$\{ \partial_\alpha, \partial_\beta \} = 2 \delta_{\alpha\beta}$$

$$\Rightarrow \partial_x \partial_y + \partial_y \partial_x = 0$$

$$K \partial_y = \partial_y^* K = (-\partial_y) K$$

$$i \partial_y \cdot \partial_y = \partial_y \cdot i \partial_y$$

$$i \partial_y \cdot \partial_x = -\partial_x \cdot i \partial_y$$

$$\Rightarrow (*) = \left(\frac{p^2}{2m} + \frac{\hbar}{2} (p_x \partial_y - (-p_y) (-\partial_x)) \right) i \partial_y K = HT$$

Torej:

$$H | \psi \rangle = E | \psi \rangle$$

$$HT | \psi \rangle = TH | \psi \rangle = TE | \psi \rangle = E T | \psi \rangle$$

$T | \psi \rangle$ tudi lastno stanje

Ali sta ti dve lastni stanji isti?

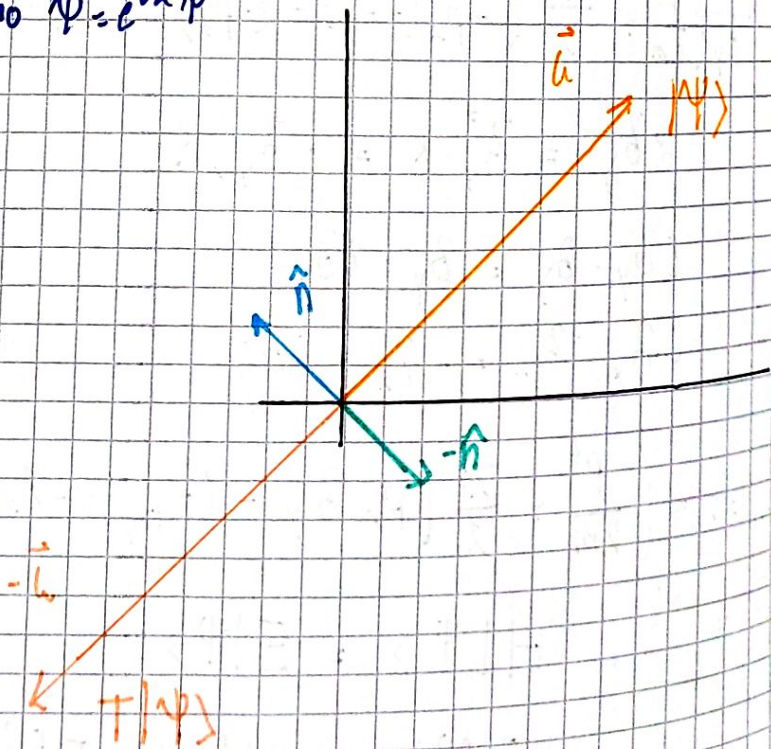
$$T^2 = (i\partial_y K)(i\partial_y K) = i\partial_y (-i)(-\partial_y) K^2 = -\partial_y^2 = -I$$

$$\langle \Psi | T\Psi \rangle = \langle T\Psi | T^2\Psi \rangle^* = \langle T\Psi | -\Psi \rangle^* = -\langle -\Psi | T\Psi \rangle = -\langle \Psi, T\Psi \rangle = 0$$

Torej sta stanji ortogonalni. Torej če imamo H invarianten na T in $T^2 = -1$ dobimo lahko z aplikiranjem T še drugo stanje. Temu se icoe **Kramersova degeneracija (Kramersov dublet)**.

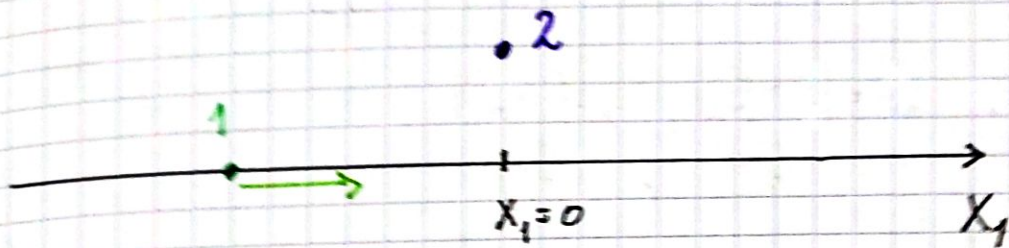
$$T \left(\frac{|\uparrow\rangle + ie^{i\phi}|\downarrow\rangle}{\sqrt{2}} \right) \rightarrow T e^{i\vec{h}\cdot\vec{r}} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{ie^{i\phi}}{\sqrt{2}} \end{pmatrix} = i\partial_y e^{-i\vec{h}\cdot\vec{r}} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{ie^{-i\phi}}{\sqrt{2}} \end{pmatrix} = e^{-i\vec{h}\cdot\vec{r}} \begin{pmatrix} -\frac{ie^{-i\phi}}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix} \stackrel{\alpha > 0 \in \mathbb{R}}{=} e^{-i\vec{h}\cdot\vec{r}} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} (+ie^{i\phi}) \end{pmatrix} = e^{-i\vec{h}\cdot\vec{r}} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{ie^{i\phi}}{\sqrt{2}} \end{pmatrix}$$

To lahko beremo fizikalno $\Psi = e^{i\alpha\phi}$



[Dva delca, ki se cutita]

$$H = \frac{p_1^2}{2m} - \frac{\lambda}{\hbar^2} \delta(x_1) \vec{S}_1 \cdot \vec{S}_2 \quad ; \quad S_1 = \frac{1}{2} \\ S_2 = 1$$



a) Pogledimo si vezan sistem

$$\vec{S} = \vec{S}_1 + \vec{S}_2 \Rightarrow S^2 = S_1^2 + S_2^2 + 2\vec{S}_1 \cdot \vec{S}_2 \quad S_z = S_{1z} + S_{2z} \\ \Rightarrow \vec{S}_1 \cdot \vec{S}_2 = \frac{1}{2}(S^2 - S_1^2 - S_2^2)$$

To vstavimo v H:

$$H = \frac{p_1^2}{2m} - \frac{\lambda}{2\hbar^2} \delta(x_1) (S^2 - S_1^2 - S_2^2)$$

$$\Rightarrow [H, S^2] = [H, S_1^2]; [H, S_2^2] = [H, S_z] = 0$$

$$[S^2, S_1^2] = [S^2, S_2^2] = [S_1^2, S_2^2] = 0$$

$$[S_1^2, S_2^2] = [S_1^2, S_z] = 0$$

$$[S_2^2, S_z] = 0$$

$H, S^2, S_1^2, S_2^2, S_z$

Skupaj komutirajo

1. delec

2. delec

1. in 2. delec

dogovor ker S_1 ločst.

$$|+\rangle = \left| \frac{1}{2} \frac{1}{2} \right\rangle$$

$$|11\rangle$$

$$|+\rangle |11\rangle = |+\rangle |11\rangle$$

$$|+\rangle = \left| \frac{1}{2} -\frac{1}{2} \right\rangle$$

$$|10\rangle$$

$$|+\rangle |10\rangle = |+\rangle |0\rangle$$

$$|1-1\rangle$$

$$|+\rangle |1-1\rangle = |+\rangle |-1\rangle$$

S_1

S_{1z}

S_2

S_{2z}

$$|+\rangle |11\rangle$$

$$|+\rangle |10\rangle$$

$$|+\rangle |1-1\rangle$$

2D

3D

privoljna baza: lastna za

$$2 \cdot 3 = 6D$$

$S_1^2, S_{1z}, S_2^2, S_{2z}$

$$S_1^2 |\uparrow\rangle |10\rangle = \hbar^2 \frac{1}{2} \left(\frac{1}{2} + 1 \right) |\uparrow\rangle |10\rangle = \frac{3}{4} \hbar^2 |\uparrow\rangle |10\rangle$$

Izberimo **bazis** z dobrim skupnim spinom

$$S^2, S_z, S_1^2, S_2^2$$

$$S_1, S_2 \Rightarrow S = |S_1 - S_2|, \dots, |S_1 + S_2|$$

$\frac{1}{2}, \quad \frac{3}{2}$

$|S_1 S_2 S S_z\rangle$ dogovor $|S S_z\rangle$ ko S_1 in S_2 ločita

$$\begin{aligned} \Rightarrow \quad & \left| \frac{1}{2} \ 1 \ \frac{1}{2} \ -\frac{1}{2} \right\rangle = \left| \frac{1}{2} \ -\frac{1}{2} \right\rangle \\ & \left| \frac{1}{2} \ 1 \ \frac{1}{2} \ \frac{1}{2} \right\rangle = \left| \frac{1}{2} \ \frac{1}{2} \right\rangle \\ & \left| \frac{1}{2} \ 1 \ \frac{3}{2} \ -\frac{3}{2} \right\rangle = \left| \frac{3}{2} \ -\frac{3}{2} \right\rangle \\ & \left| \frac{1}{2} \ 1 \ \frac{3}{2} \ -\frac{1}{2} \right\rangle = \left| \frac{3}{2} \ -\frac{1}{2} \right\rangle \\ & \left| \frac{1}{2} \ 1 \ \frac{3}{2} \ \frac{1}{2} \right\rangle = \left| \frac{3}{2} \ \frac{1}{2} \right\rangle \\ & \left| \frac{1}{2} \ 1 \ \frac{3}{2} \ \frac{3}{2} \right\rangle = \left| \frac{3}{2} \ \frac{3}{2} \right\rangle \end{aligned}$$

Torej rešujemo $H|\Psi\rangle = E|\Psi\rangle$, z nastavitvijo $|\Psi\rangle = |\phi\rangle |S S_z\rangle$

$$H|\phi\rangle |S S_z\rangle = E|\phi\rangle |S S_z\rangle$$

$$\left[\frac{p_1^2}{2m} - \frac{\lambda}{2\hbar^2} \delta(x_1) (S^2 - S_1^2 - S_2^2) \right] |\phi\rangle |S S_z\rangle = E|\phi\rangle |S S_z\rangle$$

$$\left(\frac{p_1^2}{2m} |\phi\rangle \right) |S S_z\rangle - \frac{\lambda}{2\hbar^2} \delta(x_1) |\phi\rangle |S S_z\rangle = E|\phi\rangle |S S_z\rangle$$

$$S^2 |S S_z\rangle = \hbar^2 S(S+1) |S S_z\rangle$$

$$S_1^2 |S S_z\rangle = \frac{3}{4} \hbar^2 |S S_z\rangle$$

$$S_2^2 |S S_z\rangle = 2\hbar^2 |S S_z\rangle$$

$$\frac{p_1^2}{2m} |\phi\rangle |SS_z\rangle - \frac{\lambda}{2\hbar^2} \delta(x_1) |\phi\rangle [\hbar^2 S(S+1) - \hbar^2 S_1(S_1+1) - \hbar^2 S_2(S_2+1)] |SS_z\rangle = E |SS_z\rangle |\phi\rangle$$

$$\left(\frac{p_1^2}{2m}\right) |\phi\rangle + \frac{\lambda}{2} \delta(x_1) \left(\frac{11}{4} - S(S+1)\right) |\phi\rangle = E |\phi\rangle$$

Rešujemo pravzaprav dva problema:

$$H_{3/2} = \frac{p_1^2}{2m} - \frac{\lambda}{2} \delta(x_1) \rightarrow \text{Vezano stanje (4x degeneracija)}$$

$$H_{1/2} = \frac{p_1^2}{2m} + \lambda \delta(x_1)$$

Poglejmo sipalna stanja:

$$E > 0: S_{3/2} = \begin{pmatrix} r_{3/2} & \cdot \\ t_{3/2} & \cdot \end{pmatrix}$$

$$S_{1/2} = \begin{pmatrix} r_{1/2} & \cdot \\ t_{1/2} & \cdot \end{pmatrix}$$

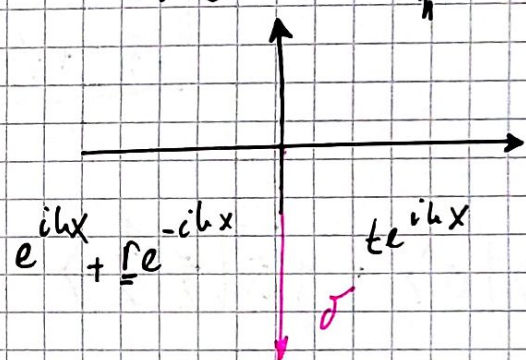
Odi zacetka bismesta:

$$H = \frac{p^2}{2m} - \lambda \delta(x)$$

$$E_0 = -\frac{\hbar^2 \lambda^2}{2m}; \quad \alpha = \frac{m\lambda}{\hbar^2}$$

$$\psi_0 = \sqrt{\alpha} e^{-\alpha|x|}$$

$$E > 0: \quad k = \frac{\sqrt{2mE}}{\hbar}$$



$$S = \frac{1}{\alpha + ik} \begin{pmatrix} -\alpha & ik \\ ik & -\alpha \end{pmatrix}$$

Taj so sipalna stanja (vpadni val iz leve) pri energiji $E > 0$:

$$S = \frac{3}{2}: \quad \left(e^{ikx_1} + r_{3/2} e^{-ikx_1} \right) \left| \frac{3}{2} S_z \right\rangle \quad \left| t_{3/2} e^{ikx_1} \right| \left| \frac{3}{2} S_z \right\rangle$$

$$S = \frac{1}{2}: \quad \left(e^{ikx_1} + r_{1/2} e^{-ikx_1} \right) \left| \frac{1}{2} S_z \right\rangle \quad \left| t_{1/2} e^{ikx_1} \right| \left| \frac{1}{2} S_z \right\rangle$$

Torej imamo 4 imamo 12 sipalnih stanj (še 6 za val iz desne) in $E < 0$ vezana stanja. To je celotna baza našega problema.

Rešujemo problem sipanja lo delec 1 prihaja z $E > 0$ iz leve mimo deka z $S_{zz} = 0$

$$\Rightarrow e^{ikx_1} |\uparrow\rangle |0\rangle ; k = \sqrt{\frac{2mE}{\hbar^2}}$$



Rubimo pretvoriti med bazama. To naredimo z Clebsch-Gordanovimi koeficienti.

	$1 \times \frac{1}{2}$	$\frac{3}{2}$				
		$\frac{3}{2}$	$\frac{3}{2}$	$\frac{1}{2}$		
$+1$	$+\frac{1}{2}$	1	$+\frac{1}{2}$	$+\frac{1}{2}$		
	$+1$	$-\frac{1}{2}$	$\frac{1}{3}$	$\frac{2}{3}$	$\frac{3}{2}$	$\frac{1}{2}$
	0	$+\frac{1}{2}$	$\frac{2}{3}$	$-\frac{1}{3}$	$-\frac{1}{2}$	$-\frac{1}{2}$
		0	$-\frac{1}{2}$	$\frac{2}{3}$	$\frac{1}{3}$	$\frac{3}{2}$
		-1	$+\frac{1}{2}$	$\frac{1}{3}$	$-\frac{2}{3}$	$-\frac{3}{2}$
				-1	$-\frac{1}{2}$	1

$$|\uparrow\rangle |0\rangle = \sqrt{\frac{2}{3}} \left| \frac{3}{2} \frac{1}{2} \right\rangle - \sqrt{\frac{1}{3}} \left| \frac{1}{2} \frac{1}{2} \right\rangle$$

$$\sqrt{\frac{2}{3}} \left(e^{ikx_1} + r_{3/2} e^{-ikx_1} \right) \left| \frac{3}{2} \frac{1}{2} \right\rangle - \sqrt{\frac{1}{3}} \left(e^{ikx_1} + r_{1/2} \right) \left| \frac{1}{2} \frac{1}{2} \right\rangle \leftarrow \text{Vpadni in odbiti}$$

$$\sqrt{\frac{2}{3}} t_{3/2} e^{ikx_1} \left| \frac{3}{2} \frac{1}{2} \right\rangle - \sqrt{\frac{1}{3}} t_{1/2} e^{ikx_1} \left| \frac{1}{2} \frac{1}{2} \right\rangle \leftarrow \text{Prepušeni}$$

Vprašanja in meritve delamo bolj v produktni bazi kot v bazi z dobrim skupnim spinom. Spet uporabimo tabele, da transformiramo

$$\left| \frac{3}{2} \frac{1}{2} \right\rangle = \sqrt{\frac{1}{3}} |\downarrow\rangle |1\rangle + \sqrt{\frac{2}{3}} |\uparrow\rangle |0\rangle$$

$$\left| \frac{1}{2} \frac{1}{2} \right\rangle = \sqrt{\frac{2}{3}} |\downarrow\rangle |1\rangle - \sqrt{\frac{1}{3}} |\uparrow\rangle |0\rangle$$

$$\sqrt{\frac{2}{3}} (e^{i\alpha x_1} + r_{3/2} e^{-i\alpha x_1}) \left[\sqrt{\frac{1}{3}} |\downarrow\rangle|1\rangle + \sqrt{\frac{2}{3}} |\uparrow\rangle|0\rangle \right] - \sqrt{\frac{1}{3}} (e^{i\alpha x_1} + r_{1/2} e^{-i\alpha x_1}) \cdot \left[\sqrt{\frac{2}{3}} |\downarrow\rangle|1\rangle - \sqrt{\frac{1}{3}} |\uparrow\rangle|0\rangle \right]$$

$$\left[\frac{\sqrt{2}}{3} (e^{i\alpha x_1} + r_{3/2} e^{-i\alpha x_1}) - \frac{\sqrt{2}}{3} (e^{i\alpha x_1} + r_{1/2} e^{-i\alpha x_1}) \right] |\downarrow\rangle|1\rangle +$$

$$+ \left[\frac{2}{3} (e^{i\alpha x_1} + r_{3/2} e^{-i\alpha x_1}) + \frac{1}{3} (e^{i\alpha x_1} + r_{1/2} e^{-i\alpha x_1}) \right] |\uparrow\rangle|0\rangle$$

$$e^{i\alpha x_1} |\uparrow\rangle|0\rangle + e^{-i\alpha x_1} \left(\frac{\sqrt{2}}{3} r_{3/2} - \frac{\sqrt{2}}{3} r_{1/2} \right) |\downarrow\rangle|1\rangle + e^{-i\alpha x_1} \left(\frac{2}{3} r_{3/2} + \frac{1}{3} r_{1/2} \right) |\uparrow\rangle|0\rangle$$

$$e^{i\alpha x_1} \left(\frac{\sqrt{2}}{3} t_{3/2} - \frac{\sqrt{2}}{3} t_{1/2} \right) |\downarrow\rangle|1\rangle + e^{i\alpha x_1} \left(\frac{2}{3} t_{3/2} + \frac{1}{3} t_{1/2} \right) |\uparrow\rangle|0\rangle$$

Ubištv element:
12x12 matrice

Veljamo lahko 4 različne verjetnosti:

$$R_{\downarrow\uparrow\uparrow} = |r_{\downarrow\uparrow\uparrow}|^2 = \left| \frac{\sqrt{2}}{3} r_{3/2} - \frac{\sqrt{2}}{3} r_{1/2} \right|^2 = \frac{2}{9} |r_{3/2}|^2 + \frac{2}{9} |r_{1/2}|^2 - 2 \operatorname{Re}(r_{3/2}^* r_{1/2}) \cdot \frac{2}{9}$$

$$R_{\uparrow\uparrow\uparrow} = |r_{\uparrow\uparrow\uparrow}|^2 = \left| \frac{2}{3} r_{3/2} + \frac{1}{3} r_{1/2} \right|^2 = \frac{4}{9} |r_{3/2}|^2 + \frac{1}{9} |r_{1/2}|^2 + \frac{4}{9} \operatorname{Re}(r_{3/2}^* r_{1/2})$$

$$T_{\uparrow\uparrow} = |t_{\uparrow\uparrow}|^2 = \dots$$

$$T_{\downarrow\uparrow} = |t_{\downarrow\uparrow}|^2 = \dots$$

Interferenčni členi

Če bi gledali celotno odbornost: $R = R_{\downarrow\uparrow\uparrow} + R_{\uparrow\uparrow\uparrow} = \frac{2}{9} |r_{3/2}|^2 + \frac{1}{9} |r_{1/2}|^2$

Podobno za celotno prepustnost: $T = \frac{2}{9} |t_{3/2}|^2 + \frac{1}{9} |t_{1/2}|^2$

Preverimo če res velja $T+R=1$

$$T+R = \frac{2}{3} \left(|r_{3/2}|^2 + |t_{3/2}|^2 \right) + \frac{1}{3} \left(|r_{1/2}|^2 + |t_{1/2}|^2 \right) = 1$$

Iz pogoja za unitarnost sipalne matrice.

To smo izpeljali brez da bi bile upoštevali delto; torej šisto splošno.

Teorija Motnje

["Anharmoni" linearni oscilator]

$$H = \underbrace{\frac{p^2}{2m}}_{H_0} + \frac{1}{2} kx^2 + \underbrace{\lambda x^4}_{H'}$$

$$H_0 |n\rangle^0 = E_n^0 |n\rangle^0$$

$$E_n^0 = \hbar \omega \left(\frac{1}{2} + n \right); \quad n=0,1,2,\dots$$

} Nemoten oscilator

$$E_n + E_n^0 + \underbrace{\langle n | H' | n \rangle^0}_{\text{1. red teorije motnje}} + \dots$$

1. red teorije motnje
za nedegenerirana stanja

Dogovor:

$$|n\rangle^0 \Rightarrow |n\rangle$$

~~Klasični~~ Lastna stanja
nemotnega.

$$X = \frac{x_0}{\sqrt{2}} (a^\dagger + a)$$

$$X^2 = \frac{x_0^2}{2} (a^\dagger + a)^2$$

$$\langle n | \lambda x^4 | n \rangle = \lambda \langle x^2 n | x^2 n \rangle$$

$$\begin{aligned} x^2 &= \frac{x_0^2}{2} (a^{\dagger 2} + a a^{\dagger} + a^{\dagger} a + a^2) = \\ &= \frac{x_0^2}{2} (a^{\dagger 2} + 1 + 2a^{\dagger} a + a^2) \end{aligned}$$

$$|x^2 n\rangle = \frac{x_0^2}{2} (a^{\dagger 2} |n\rangle + |n\rangle + 2a^{\dagger} a |n\rangle + a^2 |n\rangle)$$

$$= \frac{x_0^2}{2} (\sqrt{(n+1)(n+2)} |n+2\rangle + |n\rangle + 2n |n\rangle + \sqrt{n(n-1)} |n-2\rangle)$$

$$\Rightarrow \lambda \langle x^2 n | x^2 n \rangle = \lambda \frac{x_0^4}{4} [(n+1)(n+2) + (2n+1)^2 + n(n-1)] =$$

$$= \lambda \frac{x_0^4}{4} [n^2 + 3n + 2 + 4n^2 + 4n + 1 + n^2 - n] =$$

$$= \lambda \frac{x_0^4}{4} [6n^2 + 6n + 3] = \frac{3}{4} x_0^4 \lambda [2n^2 + 2n + 1] =$$

$$= \frac{3x_0^4 \lambda}{4} [2n^2 + 2n + 1]$$

Črna so energije v prvem redu popravila:

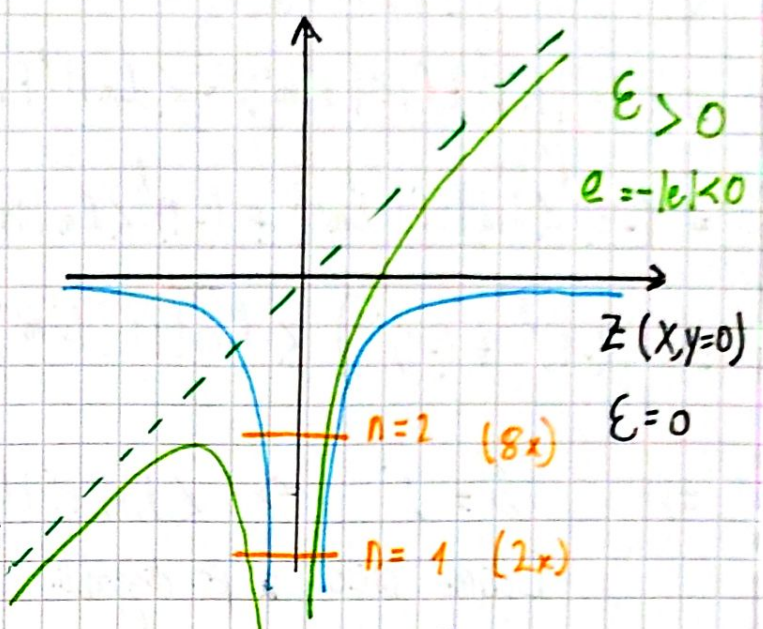
$$E_n = \hbar \omega (n + \frac{1}{2}) + \frac{3x_0^4}{4} \lambda [2n^2 + 2n + 1]$$

$$E_{n+1} - E_n = \hbar \omega + \alpha n$$

Wahrscheinlichkeit Vordruck atom v \vec{E}

$$H = H_0 + H'$$

$$= \frac{p^2}{2m} - \frac{e^2}{4\pi\epsilon_0 r} - e\epsilon Z$$



Unveränd. Basis

- $|l m \rangle |n s \rangle$
- \downarrow
- $|0 0 \rangle$
- $|1 1 \rangle$
- $|1 0 \rangle$
- $|1 -1 \rangle$

Naredimo perturbacijski popravek 1. reda

$$\begin{matrix} \langle 0 0 | \\ \langle 1 1 | \\ \langle 1 0 | \\ \langle 1 -1 | \end{matrix} \begin{bmatrix} |0 0 \rangle & |1 1 \rangle & |1 0 \rangle & |1 -1 \rangle \\ \cdot 0 & 0 & M & 0 \\ 0 & 0 & 0 & 0 \\ M^* & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Hočemo računati čim manj matričnih elementov zato uporabimo nekaj fundamentalnih dejstev in lahko hitro ugotovimo, da jih je veliko enostavnih 0.

$$1) [H', L_z] = 0, [H, L_z] = 0 \Rightarrow \langle l m | H' | l' m' \rangle = 0$$

za $m \neq m'$

$$2) P: \vec{r} \rightarrow -\vec{r} \quad P^2 \psi(\vec{r}) = \lambda^2 \psi(\vec{r}) = \psi(\vec{r}); \quad \lambda = \pm 1$$

$$[H_0, P] = 0$$

$$\{H', P\} = 0$$

$$3) \psi_{nlm}(\vec{r}) = R_{nl}(r) Y_{lm}(\theta, \phi)$$

$$P Y_{lm}(\theta, \phi) = (-1)^l Y_{lm}(\theta, \phi)$$

$$\langle l m | \{H', P\} | l' m' \rangle = 0$$

$$= \langle l m | H'P + PH' | l' m' \rangle = \langle l m | H'P | l' m' \rangle + \langle l m | PH' | l' m' \rangle =$$

$$= (-1)^l \langle l m | H' | l' m' \rangle + (-1)^{l'} \langle l m | H' | l' m' \rangle =$$

$$= \left((-1)^{l'} + (-1)^l \right) \langle l m | H' | l' m' \rangle$$

$$\Rightarrow l = l' \Rightarrow \langle l m | H' | l' m' \rangle = 0$$

Dobimo ničle a po diagonali.

Zračunajmo tisto kar ostane:

$$M = \langle 00 | H' | 10 \rangle = \int dx dy dz R_{20}^* Y_{00}^* R_{21}(r) Y_{10}(-e\epsilon z)$$

$$= \int_0^\infty r^2 dr \int_0^{2\pi} d\phi \int_0^\pi \sin\theta \frac{2}{(2r_B)^{3/2}} \left(1 - \frac{r}{2r_B}\right) e^{-r/2r_B} \frac{1}{\sqrt{4\pi}} \frac{1}{\sqrt{3}} \frac{1}{(2r_B)^{3/2}} \frac{r}{r_B} e^{-r/2r_B}$$

$$\cdot \frac{\sqrt{3}}{\sqrt{4\pi}} \cos\theta (-e\epsilon r \cos\theta) =$$

$$= -\frac{e\epsilon}{(2r_B)^3} \frac{2}{4\pi} \int_0^\infty r^2 dr \left(1 - \frac{r}{2r_B}\right) e^{-r/2r_B} \frac{r^2}{r_B} e^{-r/2r_B} \int_{-1}^1 d(\cos\theta) \cos^2\theta \int_0^{2\pi} d\phi =$$

$$= -\frac{2}{3} \frac{e\epsilon}{(2r_B)^3} \int_0^\infty d\left(\frac{r}{r_B}\right) r_B \left(\frac{r}{r_B}\right)^2 \left(1 - \frac{r}{2r_B}\right) e^{-\frac{r}{r_B}} \left(\frac{r}{r_B}\right)^2 r_B =$$

$$= -\frac{e\epsilon}{12} r_B \int_0^\infty du \left(u^4 - \frac{1}{2}u^5\right) e^{-u} = -\frac{e\epsilon}{12} r_B \left(\Gamma(3) - \frac{1}{2}\Gamma(4)\right)$$

$$= -e\epsilon r_B 2 \cdot \left(-\frac{3}{2}\right) = \underline{\underline{3e\epsilon r_B}}$$

lahko smo zapisali matriko motnje, ki jo moramo sedaj diagonalizirati.

Naredimo tudi bločna

$$\begin{array}{l}
 \langle 00 | \\
 \langle 10 | \\
 \langle 11 | \\
 \langle 1-1 |
 \end{array}
 \begin{array}{c}
 |00\rangle \quad |10\rangle \quad |11\rangle \quad |1-1\rangle \\
 \left[\begin{array}{cccc}
 0 & M & & \\
 M^* & 0 & & \\
 & & 0 & \\
 & & & 0
 \end{array} \right]
 \end{array}$$

že diag $\lambda_{1,2} = 0$
lastna vektorja sta $|11\rangle, |1-1\rangle$

Te dve stanji torej ne čvsta motnje.

$$\det \begin{pmatrix} -\lambda & M \\ M & -\lambda \end{pmatrix} = \lambda^2 - M^2 = 0 \Rightarrow \lambda_{3,4} = \pm M$$

$$1.) \lambda = -M = -3|e| \epsilon r_B$$

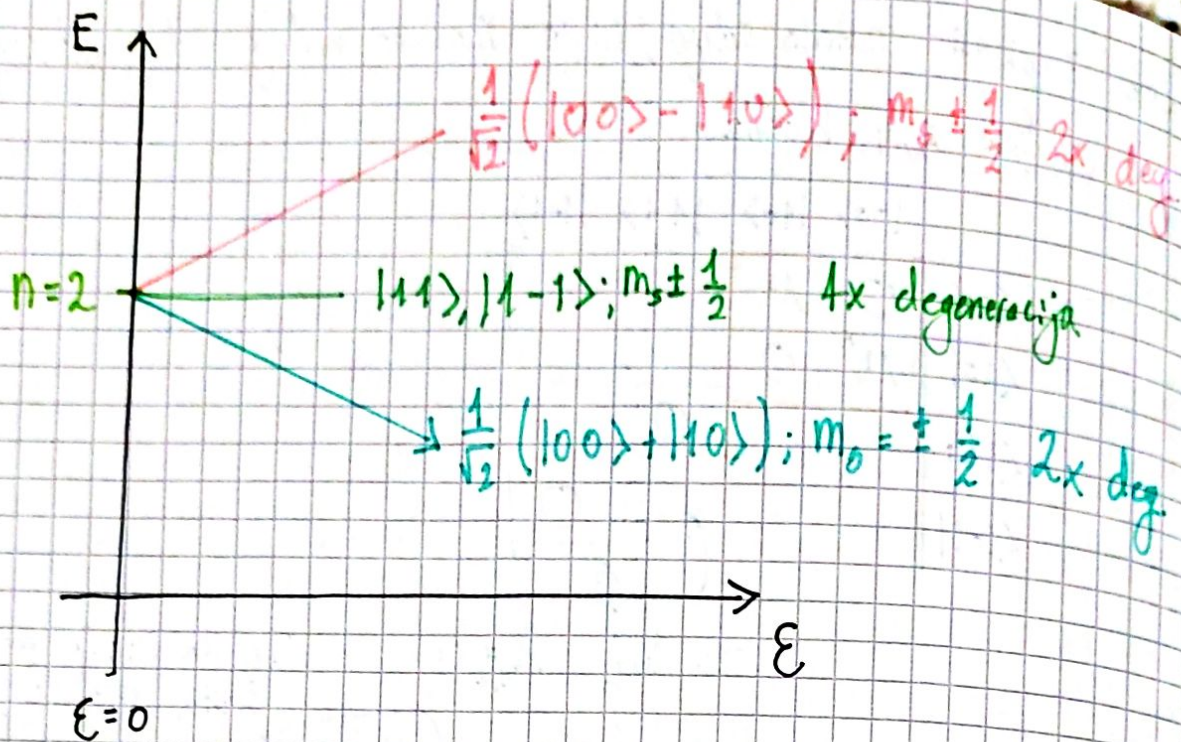
$$\begin{pmatrix} M & M \\ M & M \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \alpha + \beta = 0 \Rightarrow \alpha = -\beta$$

Torej je lastno stanje $\frac{1}{\sqrt{2}} (|00\rangle - |10\rangle)$

$$2.) \lambda = M = -3|e| \epsilon r_B$$

$$\begin{pmatrix} -M & M \\ M & -M \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \alpha = \beta$$

Torej je lastno stanje $\frac{1}{\sqrt{2}} (|00\rangle + |10\rangle)$



Recimo: $\frac{1}{\sqrt{2}}(|00\rangle - |10\rangle) \equiv |- \rangle$

$\frac{1}{\sqrt{2}}(|00\rangle + |10\rangle) \equiv | + \rangle$

Izračunajmo:

$\langle - | z | - \rangle = \frac{1}{\sqrt{2}} (\langle 00 | - \langle 10 |) z \frac{1}{\sqrt{2}} (|00\rangle - |10\rangle) =$

$= \frac{1}{2} (-\langle 00 | z | 10 \rangle - \langle 10 | z | 00 \rangle) =$

$= \frac{1}{2} (-\langle 00 | z | 10 \rangle - \langle 00 | z | 10 \rangle^*) = -\text{Re}(\langle 00 | z | 10 \rangle) =$

$\langle 00 | H' | 10 \rangle = 3eE r_B$

$\langle 00 | z | 10 \rangle = \frac{1}{eE} \langle 00 | H' | 10 \rangle = -3r_B$

$= + r_B$

Drugi se pa premakne ravno v nasprotno smer

$\langle + | r_B | + \rangle = -3r_B$

Samo
 mešani
 člani ostanejo
 (zaradi pomoči
 bra ket in liti z)